This listing of claims will replace all prior versions, and listings, of claims in the application:

Listing of Claims:

1. (Currently Amended) A method for making a plurality of bends in a conduit using a mechanical bending device, the method comprising:

receiving a desired offset;

receiving an actual degree;

automatically determining a distance value as a trigonometric function of ~~using~~ the desired offset and the actual degree, wherein the distance value comprises a desired relationship between first and second bend positions; ~~and~~

outputting the distance value; and

bending the conduit using the distance value.

2. (Original) The method of claim 1, wherein automatically determining the distance value further includes determining the second bend position.

3. (Original) The method of claim 1, wherein automatically determining the distance value further includes using a reference position to determine the second bend position.

4. (Canceled)

5. (Currently Amended) The method of claim 1, wherein automatically determining the distance value further includes accessing a memory and correlating at least one of the actual degree ~~angle~~ and the offset to the distance value.

6. (Original) The method of claim 1, wherein automatically determining the distance value further includes determining a distance between respective centers of the first and second bend positions.

7. (Original) The method of claim 1, further comprising bending the conduit using the distance value.

8. (Original) The method of claim 7, wherein bending the conduit further includes repositioning the conduit while the conduit remains in the mechanical bending device.

9. (Original) The method of claim 7, wherein bending the conduit further includes making a bend at the second bend position including the actual angle.

10. (Currently Amended) The method of claim 7, wherein bending the conduit further includes using a position indicating device to bend the conduit the actual degree ~~angle~~.

11. (Currently Amended) The method of claim 7, wherein bending the conduit further includes signaling an ~~the~~ installer when the actual degree ~~angle~~ is achieved.

12. (Original) The method of claim 1, wherein receiving the actual degree further includes determining the actual degree.

13. (Original) The method of claim 1, wherein receiving the actual degree further includes automatically determining the actual degree.

14. (Original) The method of claim 1, wherein receiving the actual degree further includes determining the actual degree while using false zero mode.

15. (Original) The method of claim 1, further comprising removably attaching the bend determining device to at least one of the mechanical bending device and the conduit.

16. (Currently Amended) An apparatus, comprising:

a bend determining device for receiving a desired offset and an actual angle, the bend determining device having a processor configured to execute program code for automatically determining using a trigonometric function a distance value indicative of where a second bend of an offset should be on a conduit using the desired offset and the actual angle; and

a display in communication with the bend determining device for outputting the distance value to an installer.

17. (Currently Amended) The apparatus of claim 16, further comprising a position indicating device configured to initiate a signal in response to contacting ~~automatically detecting a preset position of~~ at least one of a mechanical bending device and the conduit.

18. (Original) The apparatus of claim 16, further comprising a mechanical bending device configured to bend the conduit.

19. (Original) The apparatus of claim 16, wherein the bend determining device automatically determines the actual angle.

20. (Original) The apparatus of claim 16, further comprising an attachment mechanism for attaching the bend determining device to at least one of a bender and the conduit.

21. (Original) The apparatus of claim 16, wherein the bend determining device further includes at least one of a: protractor, measuring device, level holder, conversion table and a position indicating device carrier.

22. (Original) The apparatus of claim 16, wherein the bend determining device determines the distance value while the conduit remains in the mechanical bending device.

23. (Original) The apparatus of claim 16, further comprising a reference position on the conduit.

24. (Original) The apparatus of claim 16, wherein the distance value equals a distance between respective centers of the first and second bend positions.

25. (Original) The apparatus of claim 16, further comprising a protractor that operates in false zero mode.

26. (Canceled)

27. (Canceled)

28. (Canceled)